

Global well-posedness and attractors for the hyperbolic Cahn-Hilliard-Oono equation in \mathbb{R}^3

Anton Savostianov, Sergey Zelik

University of Surrey, UK



Nizhny Novgorod, Russia

July, 2015

Outline

- 1 Statement of the problem
- 2 Overview
- 3 Basic definitions of the attractor theory
- 4 Main result
- 5 Scheme of the proof: existence of the attractor
- 6 Scheme of the proof: finite fractal dimension
- 7 Final remark

Statement of the problem

We consider the so called hyperbolic Cahn-Hilliard-Oono equation

$$\varepsilon \partial_t^2 u + \partial_t u + \alpha u + \Delta_x (\Delta_x u - f(u) + g) = 0, \quad x \in \Omega, \quad (1)$$

$$(u, \partial_t u)|_{t=0} = (u_0, u'_0) \in \mathcal{E} := (\dot{H}^1 \cap \dot{H}^{-1}) \times \dot{H}^{-1} \quad (2)$$

where $\Omega = \mathbb{R}^3$ and

- 1 $\varepsilon = 1$ and $\alpha > 0$;
- 2 $g = g(x) \in \dot{H}^1$;
- 3 $f \in C^2(\mathbb{R})$ such that

$$f(u)u \geq 0, \quad (3)$$

$$F(u) \leq Lf(u)u + K|u|^2, \quad F(u) = \int_0^u f(v)dv, \quad L, K \geq 0, \quad (4)$$

$$|f''(u)| \leq C(1 + |u|^q), \quad q \in [0, 3). \quad (5)$$

Overview: parabolic case

$\alpha = 0$, J. Cahn, J. Hilliard 1958:

$$\partial_t u + \alpha u + \Delta_x (\Delta_x u - f(u) + g) = 0, \quad x \in \Omega.$$

Ω - bdd: well understood, see e. g.

- 1 A. Novick-Cohen 1998;
- 2 R. Temam 1988;
- 3 L. Cherfils, A. Miranville, S. Zelik 2011;

Overview: parabolic case

$\alpha = 0$, J. Cahn, J. Hilliard 1958:

$$\partial_t u + \alpha u + \Delta_x (\Delta_x u - f(u) + g) = 0, \quad x \in \Omega.$$

Ω - bdd: well understood, see e. g.

- 1 A. Novick-Cohen 1998;
- 2 R. Temam 1988;
- 3 L. Cherfils, A. Miranville, S. Zelik 2011;

$\Omega = \mathbb{R}^n$: less understood,

- 1 L. Caffarelli, N. Muler 1995;

Overview: parabolic case

$\alpha = 0$, J. Cahn, J. Hilliard 1958:

$$\partial_t u + \alpha u + \Delta_x (\Delta_x u - f(u) + g) = 0, \quad x \in \Omega.$$

Ω - bdd: well understood, see e. g.

- 1 A. Novick-Cohen 1998;
- 2 R. Temam 1988;
- 3 L. Cherfils, A. Miranville, S. Zelik 2011;

$\Omega = \mathbb{R}^n$: less understood,

- 1 L. Caffarelli, N. Muler 1995;

Restoring dissipation: Y. Oono, S. Puri 1987 - $\alpha > 0$

- 1 J. Pennant, S. Zelik 2013;

Overview: hyperbolic case, $\varepsilon > 0$

P. Galenko 2001, 2005, 2008: hyperbolic CHO equation with $\alpha = 0$.

$$\varepsilon \partial_t^2 u + \partial_t u + \alpha u + \Delta_x (\Delta_x u - f(u) + g) = 0, \quad x \in \mathbb{R}^3.$$

1 $\Omega = [0, l]$, $q \geq 0$, various BC:

A. Debussche 1991;

S. Zheng, A. Milani 2005;

S. Gatti, M. Grasselli, A. Miranville, V. Pata 2005, 2006;

Overview: hyperbolic case, $\varepsilon > 0$

P. Galenko 2001, 2005, 2008: hyperbolic CHO equation with $\alpha = 0$.

$$\varepsilon \partial_t^2 u + \partial_t u + \alpha u + \Delta_x (\Delta_x u - f(u) + g) = 0, \quad x \in \mathbb{R}^3.$$

- 1** $\Omega = [0, l]$, $q \geq 0$, various BC:
A. Debussche 1991;
S. Zheng, A. Milani 2005;
S. Gatti, M. Grasselli, A. Miranville, V. Pata 2005, 2006;
- 2** $\Omega \subset \mathbb{R}^2$ and bdd, $q \in [0, 1]$, Dirichlet BC:
M. Grasselli, G. Schimperna, S. Zelik 2009;

Overview: hyperbolic case, $\varepsilon > 0$

P. Galenko 2001, 2005, 2008: hyperbolic CHO equation with $\alpha = 0$.

$$\varepsilon \partial_t^2 u + \partial_t u + \alpha u + \Delta_x (\Delta_x u - f(u) + g) = 0, \quad x \in \mathbb{R}^3.$$

1 $\Omega = [0, l]$, $q \geq 0$, various BC:

A. Debussche 1991;

S. Zheng, A. Milani 2005;

S. Gatti, M. Grasselli, A. Miranville, V. Pata 2005, 2006;

2 $\Omega \subset \mathbb{R}^2$ and bdd, $q \in [0, 1]$, Dirichlet BC:

M. Grasselli, G. Schimperna, S. Zelik 2009;

3 $\Omega \subset \mathbb{R}^3$ and bdd, Dirichlet BC:

M. Grasselli, G. Schimperna, S. Zelik 2010.

No uniqueness is known in $L^\infty([0, T]; H_0^1(\Omega) \times H^{-1}(\Omega))$ even for bdd f .

Overview: hyperbolic case, $\varepsilon > 0$

Notations

(\cdot, \cdot) - scalar product in L^2 , $\|\cdot\|$ -norm in L^2 ;

$$\xi_u := (u, \partial_t u), \|\xi_u(t)\|_{\mathcal{E}}^2 = \|u(t)\|_{\dot{H}^1}^2 + \alpha \|u(t)\|_{\dot{H}^{-1}}^2 + \|\partial_t u(t)\|_{\dot{H}^{-1}}^2.$$

Overview: hyperbolic case, $\varepsilon > 0$

Notations

(\cdot, \cdot) - scalar product in L^2 , $\|\cdot\|$ -norm in L^2 ;

$\xi_u := (u, \partial_t u)$, $\|\xi_u(t)\|_{\mathcal{E}}^2 = \|u(t)\|_{\dot{H}^1}^2 + \alpha \|u(t)\|_{\dot{H}^{-1}}^2 + \|\partial_t u(t)\|_{\dot{H}^{-1}}^2$.

Energy identity

$$\frac{d}{dt} \left(\frac{1}{2} \|\xi_u\|_{\mathcal{E}}^2 + (F(u), 1) - (g, u) \right) + \|\partial_t u\|_{\dot{H}^{-1}}^2 = 0.$$

Overview: hyperbolic case, $\varepsilon > 0$

Notations

(\cdot, \cdot) - scalar product in L^2 , $\|\cdot\|$ -norm in L^2 ;

$\xi_u := (u, \partial_t u)$, $\|\xi_u(t)\|_{\mathcal{E}}^2 = \|u(t)\|_{\dot{H}^1}^2 + \alpha \|u(t)\|_{\dot{H}^{-1}}^2 + \|\partial_t u(t)\|_{\dot{H}^{-1}}^2$.

Energy identity

$$\frac{d}{dt} \left(\frac{1}{2} \|\xi_u\|_{\mathcal{E}}^2 + (F(u), 1) - (g, u) \right) + \|\partial_t u\|_{\dot{H}^{-1}}^2 = 0.$$

Definition 1

Function u such that $\xi_u(t) \in L^\infty([0, T]; \mathcal{E})$ to be called **energy solution** of (1)-(2) on $[0, T]$ if it solves the problem in the sense of distributions and $\xi_u(0) = (u_0, u'_0)$.

Overview: hyperbolic case, $\varepsilon > 0$

Theorem 1 (Existence of Energy Solutions and Dissipative Estimate)

Let f satisfies dissipative and growth assumptions, then problem (1)-(2) possesses global energy solution u such that $\xi_u(t) \in L^\infty(\mathbb{R}^+; \mathcal{E})$ and for all $t \geq 0$

$$\|\xi_u(t)\|_{\mathcal{E}}^2 + \int_t^{t+1} \|\partial_t u(s)\|_{H^{-1}}^2 ds \leq Q(\|\xi_u(0)\|_{\mathcal{E}}) e^{-\beta t} + Q(\|g\|_{\dot{H}^1}).$$

where $\beta > 0$ and Q is a monotone increasing function which is independent of t and u .

Overview: hyperbolic case, $\varepsilon > 0$

Theorem 1 (Existence of Energy Solutions and Dissipative Estimate)

Let f satisfies dissipative and growth assumptions, then problem (1)-(2) possesses global energy solution u such that $\xi_u(t) \in L^\infty(\mathbb{R}^+; \mathcal{E})$ and for all $t \geq 0$

$$\|\xi_u(t)\|_{\mathcal{E}}^2 + \int_t^{t+1} \|\partial_t u(s)\|_{H^{-1}}^2 ds \leq Q(\|\xi_u(0)\|_{\mathcal{E}}) e^{-\beta t} + Q(\|g\|_{\dot{H}^1}).$$

where $\beta > 0$ and Q is a monotone increasing function which is independent of t and u .

3D: no uniqueness is known even for bdd f .

Plate Equation and Variation of Constants Formula

$$\begin{cases} \partial_t^2 V + \Delta_x^2 V = \Delta_x H(t), & H(t) \in L_{loc}^1(\mathbb{R}; \dot{H}^1), \\ V|_{t=0} = V_0 \in \dot{H}^1, \quad \partial_t V|_{t=0} = V_1 \in \dot{H}^{-1}. \end{cases}$$

$$V(t) = \sin(\Delta_x t)(\Delta_x)^{-1}V_1 + \cos(\Delta_x t)V_0 + \int_0^t \sin(\Delta_x(t-s))H(s)ds.$$

Plate Equation and Variation of Constants Formula

$$\begin{cases} \partial_t^2 V + \Delta_x^2 V = \Delta_x H(t), & H(t) \in L_{loc}^1(\mathbb{R}; \dot{H}^1), \\ V|_{t=0} = V_0 \in \dot{H}^1, \quad \partial_t V|_{t=0} = V_1 \in \dot{H}^{-1}. \end{cases}$$

$$V(t) = \sin(\Delta_x t)(\Delta_x)^{-1} V_1 + \cos(\Delta_x t) V_0 + \int_0^t \sin(\Delta_x(t-s)) H(s) ds.$$

Theorem 2 (J. Ginibre, G. Velo 1985; T. Cazenave 2003)

$$\begin{cases} \partial_t U - i\Delta_x U = H(t), & H(t) \in L_{loc}^1(\mathbb{R}; \dot{H}^1), \\ U|_{t=0} = U_0 \in \dot{H}^1. \end{cases}$$

Then $U \in C(\mathbb{R}; \dot{H}^1) \cap L_{loc}^4(\mathbb{R}; L^\infty)$ and

$$\|U\|_{C([-T, T]; \dot{H}^1)} + \|U\|_{L^4([-T, T]; L^\infty)} \leq C_T \left(\|U_0\|_{\dot{H}^1} + \|H\|_{L^1([-T, T]; \dot{H}^1)} \right).$$

Definition 2 (S-solution)

Energy solution $u(t)$ of problem (1)-(2) is called S – solution iff it possesses the extra regularity $\xi_u \in C([0, T]; \mathcal{E})$ and $u \in L^4([0, T]; C_b)$.

Definition 2 (S-solution)

Energy solution $u(t)$ of problem (1)-(2) is called *S – solution* iff it possesses the extra regularity $\xi_u \in C([0, T]; \mathcal{E})$ and $u \in L^4([0, T]; C_b)$.

Theorem 3 (Existence of S-solutions and dissipative estimate)

Let f be of *subquintic* growth and satisfies dissipative assumption. Then problem (1)-(2) possesses *global S-solution* u such that $\xi_u(t) \in C_b(\mathbb{R}_+; \mathcal{E})$ and $u \in L^4_{loc}(\mathbb{R}_+; C_b)$ and *dissipative estimate* holds

$$\|\xi_u(t)\|_{\mathcal{E}}^2 + \int_t^{t+1} \|\partial_t u(s)\|_{\dot{H}^{-1}}^2 ds + \|u\|_{L^4([t, t+1]; C_b)}^2 \leq Q(\|\xi_u(0)\|_{\mathcal{E}}) e^{-\beta t} + Q(\|g\|_{\dot{H}^1}), \quad t \geq 0.$$

where $\beta > 0$ and Q is a monotone increasing function which is independent of t and u .

Uniqueness and continuous dependence S -solutions

Corollary

- 1 S -solutions *obey energy identity*, indeed $f(u) \in L^1_{loc}(\mathbb{R}_+; H^1)$;
- 2 S -solutions are *unique*. Moreover,

$$\|\xi_{u_1}(t) - \xi_{u_2}(t)\|_{\mathcal{E}} + \|u_1 - u_2\|_{L^4([t, t+1]; C_b)} \leqslant C e^{Kt} \|\xi_{u_1}(0) - \xi_{u_2}(0)\|_{\mathcal{E}},$$

where C and K depend on $\|\xi_{u_1}(0)\|_{\mathcal{E}}$, $\|\xi_{u_2}(0)\|_{\mathcal{E}}$ only.

Basic definitions

Let \mathcal{E} be a complete metric space and $S_t : \mathcal{E} \rightarrow \mathcal{E}$ be a semigroup on \mathcal{E} .

Definition 3

A subset $A \subset \mathcal{E}$ is called a **global attractor** for the dynamical system (\mathcal{E}, S_t) , if

- 1 A is compact in \mathcal{E} ;
- 2 A is invariant, i.e. $S_t A = A \forall t \geq 0$;
- 3 for any bounded set $B \subset \mathcal{E}$
 $\lim_{t \rightarrow \infty} \sup \{ \text{dist}(S_t y, A) : y \in B \} = 0$.

Theorem 4 (A. S., S. Zelik)

Let f be of *subquintic* growth and satisfies dissipative assumptions. Then the S -solution semigroup $S(t)$ associated with problem (1)-(2):

$$S_t : \mathcal{E} \rightarrow \mathcal{E}, \quad S_t \xi_0 = \xi_u(t), \quad \xi_u(0) = \xi_0,$$

possesses a global attractor \mathcal{A} in \mathcal{E} . Furthermore,

$$\|\mathcal{A}\|_{\mathcal{E}_2} \leq C_{\mathcal{A}},$$

where $\mathcal{E}_2 := \dot{H}^3 \cap \dot{H}^{-1} \times \dot{H}^1 \cap \dot{H}^{-1}$.

Basic definitions

Let \mathcal{E} be a complete metric space and $S_t : \mathcal{E} \rightarrow \mathcal{E}$ be a semigroup on \mathcal{E} .

Definition 4 (Absorbing set)

A set D to be called **absorbing** for the dynamical system (\mathcal{E}, S_t) iff:
 $\forall B \subset \mathcal{E} \exists T = T(B) : \forall t \geq T S_t B \subset D.$

Basic definitions

Let \mathcal{E} be a complete metric space and $S_t : \mathcal{E} \rightarrow \mathcal{E}$ be a semigroup on \mathcal{E} .

Definition 4 (Absorbing set)

A set D to be called **absorbing** for the dynamical system (\mathcal{E}, S_t) iff:
 \forall bdd $B \subset \mathcal{E} \exists T = T(B) : \forall t \geq T S_t B \subset D$.

Definition 5 (Asymptotic compactness)

The (\mathcal{E}, S_t) is **asymptotically compact** iff for any bdd set $B \subset \mathcal{E}$, any sequence of the initial data $\xi_n \in B$ and any sequence of times $t_n \geq 0$ such that $t_n \rightarrow +\infty$ as $n \rightarrow \infty$, the sequence

$\{S_{t_n} \xi_n\}_{n=1}^{\infty}$ is precompact in \mathcal{E} .

Classic result

R. Temam 1988; A. Babin, M. Vishik 1990.

Theorem 5 (Existence of the attractor)

Let the semi-group $S_t : \mathcal{E} \rightarrow \mathcal{E}$ possess the following properties:

- 1 The operators $S_t : \mathcal{E} \rightarrow \mathcal{E}$ are **continuous** in \mathcal{E} for every fixed t ;
- 2 (\mathcal{E}, S_t) possesses a bounded absorbing set
(= is **dissipative**);
- 3 (\mathcal{E}, S_t) is **asymptotically compact**.

Then dynamical system (\mathcal{E}, S_t) possesses a **global attractor** $\mathcal{A} \subset \mathcal{E}$, which is generated by all complete trajectories of the semi-group S_t :

$$\mathcal{A} = \mathcal{K}|_{t=0},$$

where $\mathcal{K} \subset L^\infty(\mathbb{R}, \mathcal{E})$ consists of all bounded functions $u : \mathbb{R} \rightarrow \mathcal{E}$ such that $S_h u(t) = u(t+h)$ for all $t \in \mathbb{R}$ and $h \geq 0$.

Scheme of the proof: asymptotic compactness

1. Fix bdd $B \subset \mathcal{E}$, $\{\xi_n\}_{n=1}^{\infty} \subset B$, $\{t_n\}_{n=1}^{\infty} : t_n \rightarrow +\infty$.

Scheme of the proof: asymptotic compactness

1. Fix bdd $B \subset \mathcal{E}$, $\{\xi_n\}_{n=1}^\infty \subset B$, $\{t_n\}_{n=1}^\infty : t_n \rightarrow +\infty$.
2. Consider the problem

$$\begin{cases} \partial_t^2 u_n + \partial_t u_n + \alpha u_n + \Delta_x (\Delta_x u_n - f(u_n) + g) = 0, \\ (u_n, \partial_t u_n)|_{t=-t_n} = \xi_n. \end{cases} \quad (6)$$

$$S_{t_n} \xi_n = \xi_{u_n(0)} \quad - \text{bdd by dissipativity.} \quad (7)$$

Scheme of the proof: asymptotic compactness

1. Fix bdd $B \subset \mathcal{E}$, $\{\xi_n\}_{n=1}^\infty \subset B$, $\{t_n\}_{n=1}^\infty : t_n \rightarrow +\infty$.
2. Consider the problem

$$\begin{cases} \partial_t^2 u_n + \partial_t u_n + \alpha u_n + \Delta_x (\Delta_x u_n - f(u_n) + g) = 0, \\ (u_n, \partial_t u_n)|_{t=-t_n} = \xi_n. \end{cases} \quad (6)$$

$$S_{t_n} \xi_n = \xi_{u_n}(0) \quad - \text{bdd by dissipativity.} \quad (7)$$

3.

$$\xi_{u_n}(0) \rightharpoonup \xi_u(0) \text{ a. e. wrt } x, \text{ weakly in } \mathcal{E}, \text{ where} \quad (8)$$

$u(t) \in C_b(\mathbb{R}, \mathcal{E}) \cap L^4_{loc}(\mathbb{R}, C_b)$ is a complete S-solution.

Scheme of the proof: asymptotic compactness

1. Fix bdd $B \subset \mathcal{E}$, $\{\xi_n\}_{n=1}^\infty \subset B$, $\{t_n\}_{n=1}^\infty : t_n \rightarrow +\infty$.
2. Consider the problem

$$\begin{cases} \partial_t^2 u_n + \partial_t u_n + \alpha u_n + \Delta_x (\Delta_x u_n - f(u_n) + g) = 0, \\ (u_n, \partial_t u_n)|_{t=-t_n} = \xi_n. \end{cases} \quad (6)$$

$$S_{t_n} \xi_n = \xi_{u_n}(0) \quad - \text{bdd by dissipativity.} \quad (7)$$

3.

$$\xi_{u_n}(0) \rightharpoonup \xi_u(0) \text{ a. e. wrt } x, \text{ weakly in } \mathcal{E}, \text{ where} \quad (8)$$

$u(t) \in C_b(\mathbb{R}, \mathcal{E}) \cap L^4_{loc}(\mathbb{R}, C_b)$ is a complete S-solution.

4. To prove

$$\xi_{u_n}(0) \rightarrow \xi_u(0) \text{ strongly in } \mathcal{E} \quad (9)$$

It is enough

$$\|\xi_{u_n}(0)\|_{\mathcal{E}} \rightarrow \|\xi_u(0)\|_{\mathcal{E}}, \quad n \rightarrow \infty. \quad (10)$$

5. Energy method (R. Rosa et al. 1998, J. Ball 2004)

$$\bar{E}_u(t) := \frac{1}{4} \|\xi_u(t)\|_{\mathcal{E}}^2 + \delta (\partial_t u(t), (-\Delta_x)^{-1} u(t)) + \frac{\delta}{2} \|u(t)\|_{\dot{H}^{-1}}^2 + (F(u(t)), 1),$$

$\delta > 0$ - small enough.

5. Energy method (R. Rosa et al. 1998, J. Ball 2004)

$$\bar{E}_u(t) := \frac{1}{4} \|\xi_u(t)\|_{\mathcal{E}}^2 + \delta (\partial_t u(t), (-\Delta_x)^{-1} u(t)) + \frac{\delta}{2} \|u(t)\|_{\dot{H}^{-1}}^2 + (F(u(t)), 1),$$

$\delta > 0$ - small enough.

$$\frac{d}{dt} \left(\frac{1}{4} \|\xi_{u_n}(t)\|_{\mathcal{E}}^2 + \bar{E}_{u_n}(t) \right) + \beta \left(\frac{1}{4} \|\xi_{u_n}(t)\|_{\mathcal{E}}^2 + \bar{E}_{u_n}(t) \right) = -\mathcal{H}_{u_n}(t),$$

$\beta > 0$ - small enough.

$$\frac{1}{4} \|\xi_{u_n}(0)\|_{\mathcal{E}}^2 + \bar{E}_{u_n}(0) = e^{-\beta t_n} \left(\frac{1}{4} \|\xi_{u_n}(-t_n)\|_{\mathcal{E}}^2 + \bar{E}_{u_n}(-t_n) \right) - \int_{-t_n}^0 e^{\beta t} \mathcal{H}_{u_n}(t) dt.$$

By weak convergence and Fatou lemma

$$\begin{aligned}\bar{E}_u(0) &\leq \underline{\lim}_{n \rightarrow \infty} \bar{E}_{u_n}(0), \quad \int_{-\infty}^0 e^{\beta s} \mathcal{H}_u(s) ds \leq \underline{\lim}_{n \rightarrow \infty} \int_{-t_n}^0 e^{\beta s} \mathcal{H}_{u_n}(s) ds. \\ \frac{1}{4} \overline{\lim}_{n \rightarrow \infty} \|\xi_{u_n}(0)\|_{\mathcal{E}}^2 + \bar{E}_u(0) &\leq - \int_{-\infty}^0 e^{\beta s} \mathcal{H}_u(s) ds. \quad (11)\end{aligned}$$

By weak convergence and Fatou lemma

$$\begin{aligned}\bar{E}_u(0) &\leq \liminf_{n \rightarrow \infty} \bar{E}_{u_n}(0), \quad \int_{-\infty}^0 e^{\beta s} \mathcal{H}_u(s) ds \leq \liminf_{n \rightarrow \infty} \int_{-t_n}^0 e^{\beta s} \mathcal{H}_{u_n}(s) ds. \\ \frac{1}{4} \overline{\lim}_{n \rightarrow \infty} \|\xi_{u_n}(0)\|_{\mathcal{E}}^2 + \bar{E}_u(0) &\leq - \int_{-\infty}^0 e^{\beta s} \mathcal{H}_u(s) ds. \quad (11)\end{aligned}$$

However, since u obeys energy identity,

$$\frac{1}{4} \|\xi_u(0)\|_{\mathcal{E}}^2 + \bar{E}_u(0) = - \int_{-\infty}^0 e^{\beta s} \mathcal{H}_u(s) ds. \quad (12)$$

Thus

$$\overline{\lim}_{n \rightarrow \infty} \|\xi_{u_n}(0)\|_{\mathcal{E}}^2 \leq \|\xi_u(0)\|_{\mathcal{E}}^2 \leq \liminf_{n \rightarrow \infty} \|\xi_{u_n}(0)\|_{\mathcal{E}}^2.$$

6. Smoothness of the attractor follows from its compactness.

Finite fractal dimension of the attractor

Definition 6

Fractal dimension $\dim_f^\mathcal{E} M$ of a compact set $M \subset \mathcal{E}$ in a metric space \mathcal{E} is defined by

$$\dim_f^\mathcal{E} M = \overline{\lim}_{\varepsilon \rightarrow 0} \frac{\log n(M, \varepsilon)}{\log \left(\frac{1}{\varepsilon}\right)}, \quad \text{where } n(M, \varepsilon) \text{ is the minimal number of closed } \varepsilon\text{-balls that cover } M.$$

Theorem 6 (A. S., S. Zelik)

Let f be of **subquintic** growth and satisfies dissipative assumptions. And let \mathcal{A} be the global attractor of the dynamical system associated with S -solutions of the hyperbolic CHO equation. Then

$$\dim_f^\mathcal{E} \mathcal{A} < \infty.$$

Basics of multilinear algebra

Let \mathcal{E} be a separable Hilbert space.

Definition 7 (Wedge-product)

Let $\phi_1, \dots, \phi_d \in \mathcal{E}$, then $\phi_1 \wedge \dots \wedge \phi_d$ is a d -linear antisymmetric form on \mathcal{E} defined by:

$$\phi_1 \wedge \dots \wedge \phi_d(\psi_1, \dots, \psi_d) := \det \left((\phi_i, \psi_j)_{i,j=1}^d \right), \quad \psi_1, \dots, \psi_d \in \mathcal{E}.$$

$\tilde{\Lambda}^d \mathcal{E}$ - space of all finite d -linear antisymmetric functionals that can be represented as finite linear combination of terms $\phi_1 \wedge \dots \wedge \phi_d$.

Definition 8 (Scalar product)

$$(\phi_1 \wedge \dots \wedge \phi_d, \psi_1 \wedge \dots \wedge \psi_d)_{\Lambda^d \mathcal{E}} = \det \left((\phi_i, \psi_j)_{i,j=1}^d \right)$$

Definition 9

$\Lambda^d \mathcal{E}$ - completion of $\tilde{\Lambda}^d \mathcal{E}$ with respect to $\| \cdot \|_{\Lambda^d \mathcal{E}}$.

Volume contraction factor

Definition 10 ($\Lambda^d L$)

Let $L \in \mathcal{L}(\mathcal{E}, \mathcal{E})$. Then the linear operator $\Lambda^d L$ acts on $\Lambda^d \mathcal{E}$ by:
 $(\Lambda^d L)\xi(\psi_1, \dots, \psi_d) = \xi(L^*\psi_1, \dots, L^*\psi_d)$,
where $L^* \in \mathcal{L}(\mathcal{E}, \mathcal{E})$ is the adjoint to L .

In particular, if $\xi = \phi_1 \wedge \dots \wedge \phi_d$, then
 $(\Lambda^d L)(\phi_1 \wedge \dots \wedge \phi_d) = L\phi_1 \wedge \dots \wedge L\phi_d$.

Proposition 1

Let $L \in \mathcal{L}(\mathcal{E}, \mathcal{E})$, then $\Lambda^d L \in \mathcal{L}(\Lambda^d \mathcal{E}, \Lambda^d \mathcal{E})$ and

$$\omega_d(L) := \|\Lambda^d L\|_{\Lambda^d \mathcal{E}} = \sup_{\phi_1 \wedge \dots \wedge \phi_d \neq 0} \frac{\|L\phi_1 \wedge \dots \wedge L\phi_d\|_{\Lambda^d \mathcal{E}}}{\|\phi_1 \wedge \dots \wedge \phi_d\|_{\Lambda^d \mathcal{E}}} = \sup_{\Pi \subset \mathcal{E}} \frac{\text{vol}_d(L\Pi)}{\text{vol}_d(\Pi)}$$

The Liouville formula

$$\frac{d}{dt}\phi(t) = L(t)\phi(t), \quad \phi|_{t=0} = \phi_0, \quad t \geq 0, \quad (13)$$

for some $L(t) \in L^\infty([0, T]; \mathcal{L}(\mathcal{E}))$.

Proposition 2 (Liouville formula)

Let $\phi_1(t), \dots, \phi_d(t)$ be solutions of problem (13), then

$$\frac{1}{2} \frac{d}{dt} \|\phi_1(t) \wedge \dots \wedge \phi_d(t)\|_{\Lambda^d \mathcal{E}}^2 = \text{Tr}(Q(t)L(t)Q(t)) \|\phi_1(t) \wedge \dots \wedge \phi_d(t)\|_{\Lambda^d \mathcal{E}}^2,$$

where $Q(t)$ is the orthoprojector on the d -dimensional space spanned by $\phi_1(t), \dots, \phi_d(t)$ and $\text{Tr}(\cdot)$ is a trace of the corresponding matrix.

The Liouville formula

$$\frac{d}{dt}\phi(t) = L(t)\phi(t), \quad \phi|_{t=0} = \phi_0, \quad t \geq 0, \quad (13)$$

for some $L(t) \in L^\infty([0, T]; \mathcal{L}(\mathcal{E}))$.

Proposition 2 (Liouville formula)

Let $\phi_1(t), \dots, \phi_d(t)$ be solutions of problem (13), then

$$\frac{1}{2} \frac{d}{dt} \|\phi_1(t) \wedge \dots \wedge \phi_d(t)\|_{\Lambda^d \mathcal{E}}^2 = \text{Tr}(Q(t)L(t)Q(t)) \|\phi_1(t) \wedge \dots \wedge \phi_d(t)\|_{\Lambda^d \mathcal{E}}^2,$$

where $Q(t)$ is the orthoprojector on the d -dimensional space spanned by $\phi_1(t), \dots, \phi_d(t)$ and $\text{Tr}(\cdot)$ is a trace of the corresponding matrix.

Definition 11 (d-trace $\text{Tr}_d(L)$)

Let $L \in \mathcal{L}(\mathcal{E})$, then its d -trace $\text{Tr}_d(L)$ is defined by

$$\text{Tr}_d(L) = \sup \left\{ \sum_{i=1}^d (L\psi_i, \psi_i) : \psi_i \in \mathcal{E}, (\psi_i, \psi_j) = \delta_{ij} \right\}.$$

Corollary

Let $U(t) : \mathcal{E} \rightarrow \mathcal{E}$ be the solution operator of problem (13), that is $\phi(t) = U(t)\phi_0$. Then $\omega_d(U(t)) \leq \exp\{\int_0^t \text{Tr}_d(L(s))ds\}$.

Corollary

Let $U(t) : \mathcal{E} \rightarrow \mathcal{E}$ be the solution operator of problem (13), that is $\phi(t) = U(t)\phi_0$. Then $\omega_d(U(t)) \leq \exp\{\int_0^t \text{Tr}_d(L(s))ds\}$.

Proposition 3 ($\text{Tr}_d(L)$ representation)

Let $L \in \mathcal{L}(\mathcal{E})$ be positive self-adjoint operator and let

$$\mu_k(L) = \inf_{F \subset \mathcal{E}, \dim F = k-1} \sup_{\phi \in F^\perp, \phi \neq 0} \frac{(L\phi, \phi)}{\|\phi\|^2}.$$

Then

$$\text{Tr}_d(L) = \sum_{k=1}^d \mu_k(L). \quad (14)$$

The Liouville formula with time dependent metric

J. - M. Ghidaglia, 1988: Cubic Schrodinger equation on $[0, L]$. $\mathcal{E}(t)$ - Hilbert space \mathcal{E} with family of scalar products $(\cdot, \cdot)_{\mathcal{E}(t)}$:

$$c^{-1} \|\phi\|_{\mathcal{E}}^2 \leq \|\phi\|_{\mathcal{E}(t)}^2 \leq c \|\phi\|_{\mathcal{E}}^2, \quad t \in \mathbb{R}.$$

Proposition 4 (Liouville formula)

Let equation (13) be well-posed and its solutions satisfy energy-identity of the form

$$\frac{1}{2} \frac{d}{dt} \|\phi\|_{\mathcal{E}(t)}^2 = (M(t)\phi(t), \phi(t))_{\mathcal{E}} = (M_{\mathcal{E}(t)}(t)\phi(t), \phi(t))_{\mathcal{E}(t)} \quad (*)$$

for some operators $M(t)$ and $M_{\mathcal{E}(t)}(t)$ defined from Riesz Theorem.

Then

$$\frac{1}{2} \frac{d}{dt} \|\phi_1(t) \wedge \dots \wedge \phi_d(t)\|_{\Lambda^d \mathcal{E}(t)}^2 = \text{Tr}(Q(t)M_{\mathcal{E}(t)}(t)Q(t)) \|\phi_1(t) \wedge \dots \wedge \phi_d(t)\|_{\Lambda^d \mathcal{E}(t)}^2,$$

where $Q(t)$ is orthoprojector on $\phi_1(t), \dots, \phi_d(t)$ in $\mathcal{E}(t)$.

The Liouville formula with time dependent metric

J. - M. Ghidaglia, 1988: Cubic Schrodinger equation on $[0, L]$. $\mathcal{E}(t)$ - Hilbert space \mathcal{E} with family of scalar products $(\cdot, \cdot)_{\mathcal{E}(t)}$:

$$c^{-1} \|\phi\|_{\mathcal{E}}^2 \leq \|\phi\|_{\mathcal{E}(t)}^2 \leq c \|\phi\|_{\mathcal{E}}^2, \quad t \in \mathbb{R}.$$

Proposition 4 (Liouville formula)

Let equation (13) be well-posed and its solutions satisfy energy-identity of the form

$$\frac{1}{2} \frac{d}{dt} \|\phi\|_{\mathcal{E}(t)}^2 = (M(t)\phi(t), \phi(t))_{\mathcal{E}} = (M_{\mathcal{E}(t)}(t)\phi(t), \phi(t))_{\mathcal{E}(t)} \quad (*)$$

for some operators $M(t)$ and $M_{\mathcal{E}(t)}(t)$ defined from Riesz Theorem.

Then

$$\frac{1}{2} \frac{d}{dt} \|\phi_1(t) \wedge \dots \wedge \phi_d(t)\|_{\Lambda^d \mathcal{E}(t)}^2 = \text{Tr}(Q(t)M_{\mathcal{E}(t)}(t)Q(t)) \|\phi_1(t) \wedge \dots \wedge \phi_d(t)\|_{\Lambda^d \mathcal{E}(t)}^2,$$

where $Q(t)$ is orthoprojector on $\phi_1(t), \dots, \phi_d(t)$ in $\mathcal{E}(t)$.

Lemma 1

- 1. $L \in \mathcal{L}(\mathcal{E})$, then $c^{-d} \omega_d(L, \mathcal{E}) \leq \omega_d(L, \mathcal{E}(t)) \leq c^d \omega_d(L, \mathcal{E})$;*
- 2. $M(t) \geq 0$, then $c^{-1} \text{Tr}_d(M(t), \mathcal{E}) \leq \text{Tr}_d(M_{\mathcal{E}(t)}, \mathcal{E}(t)) \leq c \text{Tr}_d(M(t), \mathcal{E})$.*

Theorem 7 (Main abstract result, A. S., S. Zelik)

Let linear problem (13) be well-posed in \mathcal{E} and its solutions $\phi(t) = U(t)\phi_0$ possess the energy identity (*). Assume $(M(t)\phi, \phi)_{\mathcal{E}} \leq (C(t)\phi, \phi)_{\mathcal{E}} + (K(t)\phi, \phi)_{\mathcal{E}}$, $\phi \in \mathcal{E}$

where

1. $(C(t)\phi, \phi)_{\mathcal{E}} \leq -\beta \|\phi\|_{\mathcal{E}}^2$, $\phi \in \mathcal{E}$, $\beta > 0$ – independent of t ;
2. $K(t)$ – positive, $(K(t)\phi, \phi) \leq (K\phi, \phi)$, $K \in \mathcal{L}(\mathcal{E})$ – compact.

Then

1. $\omega_d(U(t), \mathcal{E}) \leq e^{d \ln c + (c C_K - \frac{\beta d}{2c})t}$, where C_K depends only on K ;
2. If d is such that $C_K - \beta d/2 < 0$, then

$$\omega_d(U(t), \mathcal{E}) \leq 1/2, \text{ as long as } t \geq t_0.$$

Proof.

$$\begin{aligned} \omega_d(U(t), \mathcal{E}) &\leq c^d \omega_d(U(t), \mathcal{E}(t)) \leq \\ &c^d \exp\left\{\int_0^t \text{Tr}_d(C_{\mathcal{E}(s)}(s), \mathcal{E}(s)) + \text{Tr}_d(K_{\mathcal{E}(s)}(s), \mathcal{E}(s)) ds\right\} \leq \\ &c^d \exp\left\{\int_0^t c^{-1} \text{Tr}_d(C(s), \mathcal{E}) + c \text{Tr}_d(K(s), \mathcal{E}) ds\right\} \leq \\ &c^d \exp\left\{t(-c^{-1}\beta d + c \text{Tr}_d(K, \mathcal{E}))\right\} \leq \\ &c^d \exp\left\{t(-c^{-1}\beta d + c(C_K + \beta d c^{-2}/2))\right\}. \end{aligned}$$



Volume contraction theorem

Definition 12 (Quasidifferential)

A map $S : \mathcal{A} \rightarrow \mathcal{A}$, where \mathcal{A} is a compact subset of a Banach space \mathcal{E} is called uniform quasidifferentiable on \mathcal{A} if for any $\xi \in \mathcal{A}$ there exists $S'(\xi) \in \mathcal{L}(\mathcal{E})$:

1. $\|S(\xi_2) - S(\xi_1) - S'(\xi_1)(\xi_2 - \xi_1)\|_{\mathcal{E}} = o(\|\xi_1 - \xi_2\|_{\mathcal{E}})$, holds uniformly for all $\xi_1, \xi_2 \in \mathcal{A}$;
2. $S'(\xi) \in C(\mathcal{A}, \mathcal{L}(\mathcal{E}))$.

Theorem 8 (Main abstract result)

Let \mathcal{A} be a compact set of a Hilbert space \mathcal{E} :

1. $S\mathcal{A} = \mathcal{A}$;
2. S is quasidifferentiable on \mathcal{A} ;
3. $S'(\xi)$ contacts all d -volumes uniformly w. r. t. $\xi \in \mathcal{A}$, i. e.

$$\omega_d(\mathcal{A}, S) := \sup_{\xi \in \mathcal{A}} \omega_d(S'(\xi), \mathcal{E}) < 1.$$

Then $\dim_f^{\mathcal{E}} \mathcal{A} \leq d$.

Theorem 9

Let f be of **subquintic** growth and satisfies dissipative assumptions. Then solution operator $S(t)$ of the hyperbolic CHO equation is uniformly quasidifferentiable on the attractor \mathcal{A} :

$$\forall \xi_0 \in \mathcal{A} \quad S'(t, \xi_0) \hat{\xi} = \xi_w(t), \quad \hat{\xi} \in \mathcal{E},$$

where w solves the equation of variations

$$\begin{cases} \partial_t^2 w + \partial_t w + \alpha w + \Delta_x(\Delta_x w - f'(u)w) = 0, & x \in \mathbb{R}^3, \\ \xi_w|_{t=0} = (w_0, w'_0) = \hat{\xi}, \end{cases} \quad (\text{QD})$$

where $\xi_u(t) = S(t)\xi_0$ is S -solution hyperbolic CHO equation with initial data $\xi_0 \in \mathcal{A}$.

Obviously, we can rewrite (QD) as $\frac{d}{dt}\xi_w(t) = L(t, \xi_0)\xi_w(t)$, with

$$L(t, \xi_0) := \begin{pmatrix} 0 & 1 \\ -\alpha & -1 \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ -\Delta_x & 0 \end{pmatrix} \begin{pmatrix} \Delta_x - f'(u(t)) & 0 \\ 0 & 0 \end{pmatrix}. \quad (\text{QD}')$$

Standard argument fails:

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \left(\|\xi_w\|_{\mathcal{E}}^2 + 2\delta(\partial_t w, w)_{\dot{H}^{-1}} + \delta\|w\|_{\dot{H}^{-1}}^2 \right) = \\ - \left((1 - \delta)\|\partial_t w\|_{\dot{H}^{-1}}^2 + \delta\|w(t)\|_{\dot{H}^1}^2 + \alpha\delta\|w(t)\|_{\dot{H}^{-1}}^2 \right) \\ - (f'(u)w, \partial_t w) - \delta(f'(u)w, w), \end{aligned}$$

where $\delta > 0$ is small enough.

Indeed, assume, for simplicity, that

1. Ω - smooth and bdd;
2. $\mathcal{E} = H_0^1(\Omega) \times H^{-1}(\Omega)$;
3. $f'(u) \equiv C$, then

$(w, \partial_t w) = (K\xi_w, \xi_w)_{\mathcal{E}}$, with $K = \begin{pmatrix} 0 & 0 \\ -\Delta_x & 0 \end{pmatrix}$, and $K \in \mathcal{L}(\mathcal{E})$ is not compact!

Finite fractal dimension of the attractor: proof

IDEA: kill the $(f'(u)w, \partial_t w)$.

Let us introduce the family of equivalent norms on \mathcal{E} :

$$\|\xi_w(t)\|_{\mathcal{E}(t, \xi_0)}^2 := \|\xi_w\|_{\mathcal{E}}^2 + 2\delta(\partial_t w, w)_{\dot{H}^{-1}} + \delta\|w\|_{\dot{H}^{-1}}^2 + (f'(u)w, w) + L\|(-\Delta_x + 1)^{-1/2}(\psi_R w)\|_{L^2}^2,$$

where

$0 \leq \psi_R(x) \leq 1$, $\psi_R(x) = 1$ if $|x| \leq R - 1$, $\psi_R(x) = 0$ if $|x| \geq R$, and L, R are large enough parameters to be fixed below.

Finite fractal dimension of the attractor: proof

IDEA: kill the $(f'(u)w, \partial_t w)$.

Let us introduce the family of equivalent norms on \mathcal{E} :

$$\|\xi_w(t)\|_{\mathcal{E}(t, \xi_0)}^2 := \|\xi_w\|_{\mathcal{E}}^2 + 2\delta(\partial_t w, w)_{\dot{H}^{-1}} + \delta\|w\|_{\dot{H}^{-1}}^2 + (f'(u)w, w) + L\|(-\Delta_x + 1)^{-1/2}(\psi_R w)\|_{L^2}^2,$$

where

$0 \leq \psi_R(x) \leq 1$, $\psi_R(x) = 1$ if $|x| \leq R - 1$, $\psi_R(x) = 0$ if $|x| \geq R$, and L, R are large enough parameters to be fixed below.

We have

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \|\xi_w(t)\|_{\mathcal{E}(t, \xi_0)}^2 &= -((1 - \delta)\|\partial_t w\|_{\dot{H}^{-1}}^2 + \delta\|w(t)\|_{\dot{H}^1}^2 + \alpha\delta\|w(t)\|_{\dot{H}^{-1}}^2) - \\ &\delta(f'(u)w, w) + \frac{1}{2}(f''(u)\partial_t u, w^2) + L\|(-\Delta_x + 1)^{-1}(\psi_R w), \psi_R \partial_t w\| := \\ &\quad (M(t, \xi_0)\xi_w, \xi_w)_{\mathcal{E}}. \quad (15) \end{aligned}$$

Theorem 10 (Equivalence of the norms)

There exist constants $L, R, \delta > 0$ such that

$$c^{-1} \|\xi_w\|_{\mathcal{E}}^2 \leq \|\xi_w\|_{\mathcal{E}(t, \xi_0)}^2 \leq c \|\xi_w\|_{\mathcal{E}}^2,$$

where constant c does not depend on t and $\xi_0 \in \mathcal{A}$.

Proof.

Upper bound: trivial;

Lower bound:

$$(f'(u)w, w) =$$

$$(\psi_R f'(u)w, w) + ((1 - \psi_R)[f'(u) - f'(0)]w, w) + f'(0)((1 - \psi_R)w, w) \geq$$

$$-C(\psi_R w, w) - C\|(1 - \psi_R)u\|_{L^\infty} \|w\|_{L^2}^2 \geq$$

$$-C\|(-\Delta_x + 1)^{-1/2}(\psi_R w)\|_{L^2} \|(-\Delta_x + 1)w, w\|^{1/2} -$$

$$C\|(1 - \psi_R)u\|_{L^\infty} \|w\|_{L^2}^2 \geq$$

$$-C_\varepsilon\|(-\Delta_x + 1)^{-1/2}(\psi_R w)\|_{L^2}^2 - \varepsilon\|\xi_w\|_{\mathcal{E}}^2 - C\|(1 - \psi_R)u\|_{L^\infty} \|w\|_{L^2}^2,$$

where $\varepsilon > 0$ is arbitrary.

$$\|(1 - \psi_R)u\|_{L^\infty} \leq \|u\|_{L^2(|x| > R-1)}^{1/2} \|u\|_{H^2}^{1/2} \leq \varepsilon_1,$$

as long as $R \geq R(\varepsilon_1)$ - large enough.

$$(f'(u)w, w) \geq -C_\varepsilon\|(-\Delta_x + 1)^{-1/2}(\psi_R w)\|_{L^2}^2 - \varepsilon\|\xi_w\|_{\mathcal{E}}^2, \quad R \geq R(\varepsilon). \quad \square$$

Completion of the proof

$(M(t, \xi_0)\xi_w, \xi_w)_\mathcal{E} \leq -\gamma\|\xi_w\|_\mathcal{E}^2 + C\|\psi_R w\|^2 := -\gamma\|\xi_w\|_\mathcal{E}^2 + (K\xi_w, \xi_w)_\mathcal{E}$,
for some $\gamma, C > 0$ that do not depend on ξ_0 and t .

Indeed,

$$\begin{aligned} |(f''(u)\partial_t u, w^2)| &\leq C(|\partial_t u|, \psi_R w^2) + C((1 - \psi_R)|\partial_t u|, w^2) \leq \\ &\leq C\|\partial_t u\|_{L^3}\|\psi_R w\|_{L^2}\|w\|_{L^6} + C\|(1 - \psi_R)\partial_t u\|_{L^3}\|w\|_{L^6}\|w\|_{L^2} \leq \\ &\leq C\|\psi_R w\|_{L^2}\|\xi_w\|_\mathcal{E} + C\|(1 - \psi_R)\partial_t u\|_{L^3}\|\xi_w\|_\mathcal{E}^2. \quad (16) \end{aligned}$$

$$\begin{aligned} \|(1 - \psi_R)\partial_t u\|_{L^3} &\leq C\|\partial_t u\|_{L^3(|x|>R-1)} \leq \\ &\|\partial_t u\|_{L^2(|x|>R-1)}^\theta \|\partial_t u\|_{L^6}^{1-\theta} \leq \varepsilon, \quad (17) \end{aligned}$$

as long as $R = R(\varepsilon)$ - large enough. Thus

$$|(f''(u)\partial_t u, w^2)| \leq C\varepsilon\|\xi_w\|_\mathcal{E}^2 + C\varepsilon\|\psi_R w\|_{L^2}^2, \quad (18)$$

where $\varepsilon > 0$ is arbitrary small.

Final Remark

Remark: Strichartz estimates can be effectively used in dissipative case.

One more example: wave damped equation.

$$\partial_t^2 u + \gamma \partial_t u - \Delta_x u + u|u|^q = g(x), \quad x \in \Omega \quad (19)$$

$$\xi_u|_{t=0} = (u_0, u_1) \in \mathcal{E} := H_0^1(\Omega) \times L^2(\Omega), \quad u|_{\partial\Omega} = 0. \quad (20)$$

$q = 2$: A. Babin, M. Vishik, 1989; J. Arrieta, A. Carvalho, J. Hale, 1992;

Final Remark

Remark: Strichartz estimates can be effectively used in dissipative case.

One more example: wave damped equation.

$$\partial_t^2 u + \gamma \partial_t u - \Delta_x u + u|u|^q = g(x), \quad x \in \Omega \quad (19)$$

$$\xi_u|_{t=0} = (u_0, u_1) \in \mathcal{E} := H_0^1(\Omega) \times L^2(\Omega), \quad u|_{\partial\Omega} = 0. \quad (20)$$

$q = 2$: A. Babin, M. Vishik, 1989; J. Arrieta, A. Carvalho, J. Hale, 1992;
Strichartz estimates for wave equation:

1990-1994: M. Grillakis; L. Kapitanski; J. Shatah, M. Struwe.

Theorem 11

Let $\Omega = \mathbb{R}^3$, $0 \leq q \leq 4$, $\gamma \geq 0$, then wave equation possesses a unique energy solution such that $u \in L^5([0, T]; L^{10}(\Omega))$ -norm is finite for all $T \geq 0$.

$2 < q < 4$: E. Feireisl 1995, $\Omega = \mathbb{R}^3$; L. Kapitanski, 1995, Ω -compact manifold without boundary;

Final Remark

Remark: Strichartz estimates can be effectively used in dissipative case.

One more example: wave damped equation.

$$\partial_t^2 u + \gamma \partial_t u - \Delta_x u + u|u|^q = g(x), \quad x \in \Omega \quad (19)$$

$$\xi_u|_{t=0} = (u_0, u_1) \in \mathcal{E} := H_0^1(\Omega) \times L^2(\Omega), \quad u|_{\partial\Omega} = 0. \quad (20)$$

$q = 2$: A. Babin, M. Vishik, 1989; J. Arrieta, A. Carvalho, J. Hale, 1992;
Strichartz estimates for wave equation:

1990-1994: M. Grillakis; L. Kapitanski; J. Shatah, M. Struwe.

Theorem 11

Let $\Omega = \mathbb{R}^3$, $0 \leq q \leq 4$, $\gamma \geq 0$, then wave equation possesses a unique energy solution such that $u \in L^5([0, T]; L^{10}(\Omega))$ -norm is finite for all $T \geq 0$.

$2 < q < 4$: E. Feireisl 1995, $\Omega = \mathbb{R}^3$; L. Kapitanski, 1995, Ω -compact manifold without boundary;

N. Burq, G. Lebaou, F. Planchon, 2008: $\Omega \subset \mathbb{R}^3$ - smooth bdd with boundary;

$q = 4$: A. Savostianov, V. Kalantarov, S. Zelik, *submitted*.

Thank You!